

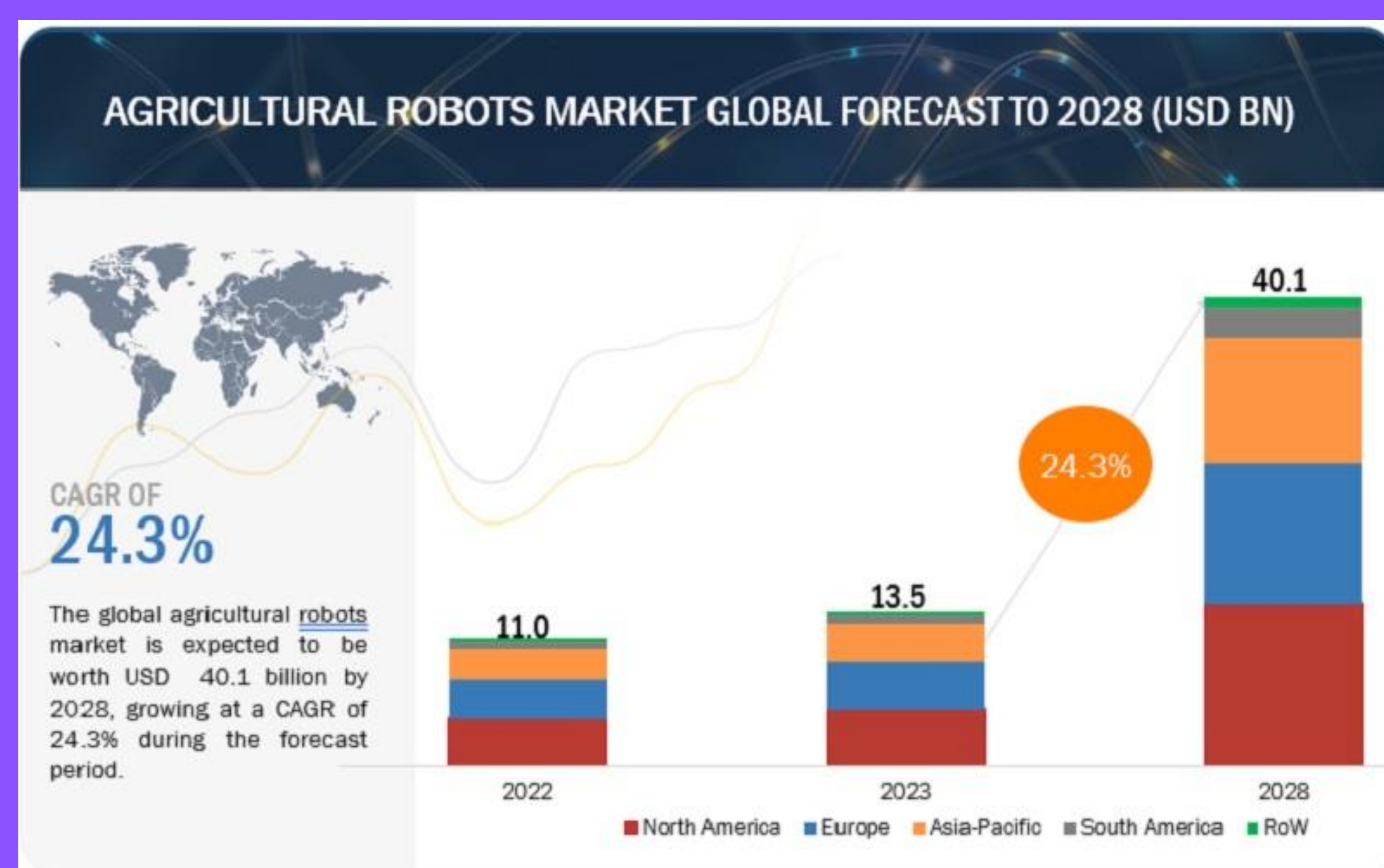


Research Question & Anticipated Product(s)

- Investigate the applications of robotics and automation in precision agriculture practice
- Develop robotic systems for high-efficiency farming operations like planting, harvesting, monitoring
- Quantify the productivity gains and return on investment from agricultural robotics
- Anticipated product: Robust AI solutions tailored for diverse agricultural environment

Professional, Legal And Ethical Issues

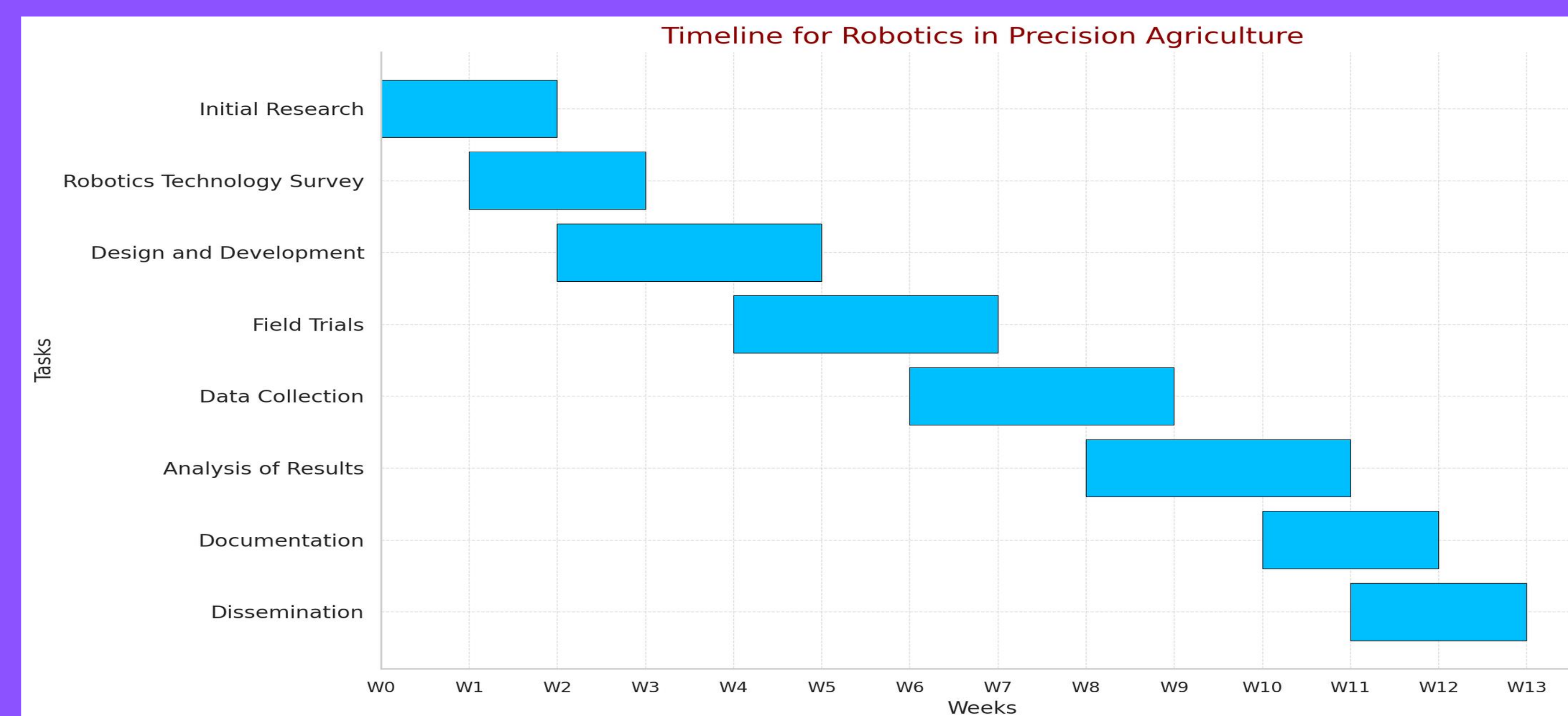
- Safety considerations of human-robot collaboration in farms
- Food safety and contamination risks from robotic equipment
- Environmental impact of robotic systems - energy use, disposal and sustainability aspects
- Economic impact on human farm labor, strategizing role transitions



Background Context of the Proposed Research

- Precision agriculture aims to optimize inputs and maximize yields through data-driven practices
- Robotics can enable automating labor-intensive tasks with higher accuracy (Bechar & Vigneault 2016)
- Key areas include seed planting, crop monitoring, targeted spraying, autonomous harvesting (Li et al. 2020)
- However, the complex, unstructured farm environments pose challenges for robotic systems (Fountas et al. 2020)

Project Scheduling



References

- Li, J., Wang, L., Liu, J. and Tang, J. (2023). ViST: A Ubiquitous Model with Multimodal Fusion for Crop Growth Prediction. ACM transactions on sensor networks, 20(1), pp.1–23. doi:[Add References here.](#)
- Yan, Q., Lou, J., Vuran, M.C. and Suat Irmak (2021). Scalable Privacy-preserving Geo-distance Evaluation for Precision Agriculture IoT Systems. ACM transactions on sensor networks, 17(4), pp.1–30. doi:[Add References here.](#)
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Evaluation Methodology

- Quantitative: Metrics like task completion time, yield output, resource utilization
- Comparative studies against human workers and existing farm machinery
- Simulation-based evaluations of robotic control and navigation under varied environments
- Pilot field deployments to study real-world performance, reliability and ease of use

Research Methodology

- Design robust robotic platforms capable of operating in fields, greenhouses, orchards
- Leverage multi-modal sensing (vision, LiDAR, hyper-spectral) for perception (Hu et al. 2023)
- Path planning, manipulation and control algorithms for autonomous field operations
- IoT and data analytics integration for precision farming decision support (Sun et al. 2023)

